

学術講演会予稿集正誤表
(Errata of Proceedings/Summarized Papers)

学術講演会セッション 番号・セッション名 (SessionNo.-Session Name)	77 二輪車の運動・制御・安全 II (77, Dynamics, Control and Safety of Two-wheeled Vehicles II)
講演タイトル (Title)	全天球画像による自動二輪車の位置計測における適切なカメラ配置の検討 (Examination of the Appropriate Alignment of Omnidirectional Cameras in the Position Measurement System for a Motorcycle Using Image Processing)
講演者名 (Speaker name) 所属名 (Affiliation)	平澤 順治 (Junji Hirasawa) 茨城高専 (Ibaraki KOSEN, College of Technology)
誤 (Incorrect)	$d_n = \frac{\tan(\alpha_{nL})\tan(\alpha_{nU})}{\tan(\alpha_{nL}) - \tan(\alpha_{nU})} \quad (7)$
正 (Correct)	$d_n = \frac{\tan(\alpha_{nL})\tan(\alpha_{nU})}{\tan(\alpha_{nL}) - \tan(\alpha_{nU})} l_n \quad (7)$